CV	Name	Description	Range	Default						
1	Loco address	Short (2 digit) address of locomotive	1 - 127	3						
2	Start voltage	Minimum speed of the locomotive	1 - 255	3						
3	Accelera- tion	This value multiplied by 0.896 is the time from stop to maximum sp	0 - 255	80						
4	Decelera- tion	This value multiplied by 0.896 is the time from maximum speed to	0 - 255	80						
5	Maximum speed	Maximum speed of the locomotive	0 - 255	255						
6	Medium speed	Medium speed of locomotive	dium speed of locomotive							
8	Manufac- turer's ID	Manufacturers's ID ESU - Writing value 8 in this CV triggers a reset factory default values	151	-						
9	Motor PWM frequency	Motor PWM frequency as a multiple of 1000 Hz	10 - 50	40						
17 18	Long address of the loco	Long address of engine ( see full manual online at www.loksound.com)								
19	Consist Address	Additional address for consist operation. Value 0 or 128 means: con address is disabled 1 – 127 consist address active, normal direction 129 – 255 consist address active reverse direction	0-255	0						
27	Brake mode	Allowed brake modes		28						
		Bit Function O   ABC braking, voltage higher on the right hand side 1   ABC braking, voltage higher on the left hand side 2   ZIMO® HLU brakes active 3   Brake on DC, if polarity against driving direction 4   Brake on DC, if polarity like driving direction 1   Loco brakes with constant brake distance, if FS=0 1	Value 1 2 4 8 16 128							
28	RailCom®	Settings for RailCom®			131					
	Configura- tion	Bit Function   0 Channel 1 Address broadcast enabled   1 Data transmission allowed on Channel   7 RailCom® Plus automatic loco recognition active	Value 1 2 128							
29	Config- uration	Calculated field. Add up the values you want to activate, then write number into CV 29.	e this		12					
	register	Bit Function	Value							
		0 Normal direction of travel Reversed direction of travel	0							
		1 14 speed steps DCC 28 or 128 speed steps DCC	0 2							
		2 Disable analog operation Enable analog operation	0							
		3 Disable RailCom® Enable RailCom®	0							
		4 Speed curve through CV 2, 6, 5 Speed curve through CV 67 - 94	0							
		5 Short addresses (CV 1) in DCC mode	0							

	Enable RailCom	8			
	4 Speed curve three	0			
	5 Speed curve three 5 Short addresses			16	
	Long addresses				
	Eong addresses		io) in Dee	1100c 32	
De	efault Function Assignment - D	IESEL	De	fault Function Assignment - S	TEAM
Func	- Effect	Volume	Func-	Effect	Volume
tion		cv	tion		CV
FO	Directional Headlights	-	FO	Directional Headlights	379
F1	Bell	283	F1	Bell	283
F2	Playable Airhorn	275	F2	Whistle	275
F3	Coupler	291	F3	Coupler sounds	315
F4	Dynamic Brake	299	F4	Coast Mode	270
F5	AUX3 (Rotary Beacon)	-	F5	(Aux3) Mars Light	379
F6	AUX1 + AUX2 (Front) Ditchlights	-	F6	(Aux2) Cab Light	379
F7	Flange Squeal	435	F7	Switching Mode	250
F8	Sound (On / Off)	259 451			259 267
10	Sound (On / On /	459	F8	Drive Sounds	475
F9	Drive Hold	-			507
F10	Locomotive (Independent)	339	F9	Heavy Load Mode	
	Brake		F10	Independent Brake	427
F11		315		Coal Shoveling	291
F12		-		Dimmer	
F13	· · · · · · · · · · · · · · · · · · ·	-		(Aux4) Class Lights	379
F14		363		Air Pump Variable Speed	299
F15	Isolation Switch	419	F15	Air Pump slow	467
F16		-		Injector	411
F17		483	F17	Automatic Brake Set/Release Off	
F18		355	F18	Ash Dump	363
F19		443	F19	Blowdown	443
	Compressor	307	F20	Safety Valve	347
F21	Air Dryler	387	F21	Air Horn	419
F22		371	F22		435
F23		379	F23	Oil Headlight (no dynamo/	
	Reverser Center (Shift 5)	411		generator)	450
F25		507	F24		459
	Manual Notching Up	-		Oil Burner Blower	307
F27	J I I I I I I I I I I I I I I I I I I I	-		Water Refil	395
F28	, in the set of the	-		Dumping	403
F29	Automatic Brake Emergency	323		Sanding Valve	339
F30	Automatic Brake	331		Curve Squeal	371
F31	Soundfader	-		Disable Brake Squeal Sound	
			F31	Sound Fader	

Make sure that Index CV 31 is set to 16 and Index CV 32 is set to 1 before changing a volume CV.

All function buttons are fully mappable. This allows you to customize your Function Assign-All function buttons are fully mappaole. This allows you to construct you in the function on how to arrange ments in any way you wish. Please see our full manual for information on how to arrange

/	Name	Descr	ription		Range	Default			
	Index register H	Shoul	16	16					
	Index register L	CV 32 257-5	0 - 4	0					
	Extended Configura-	nded 0 Enable Load control (Back-EMF) 1							
	tion #1	1	Reserved						
		2	Reserved						
		3 4	Märklin® consecutive address "low"-Bit (not for "DCC") Automatic DCC speed step detection	0,8					
			Disable DCC speed step detection	0					
		5	Enable DCC speed step detection LGB® function button mode	16					
		Э	Disable I GB® function button mode	node 0					
			Enable LGB® function button mode	32					
		6	Reserved						
		7	Märklin® consecutive address "High"-Bit (not for "DCC")						
	Analogue	Select	ion of allowed analogue modes		0 - 3	3			
	mode	Bit	Description						
		0	AC Analogue Mode ( Only LokSound V4.0)						
		Disable AC Analog Mode 0 Enable AC Analog Mode 1 1 DC Analogue mode Disable DC Analogue mode 0		-					
				0					
			Enable DC Analogue Mode 2						
	«K Slow» Cutoff	Inerna	0 - 255 0 - 255	10 10					
	BEMF Param. «K Slow»	«K» -	«K» -Portion of the PI-Controller valid for lower speed steps						
	Control	Define	Defines the Back EMF voltage, which the motor should generate at						
	Reference voltage	value	maximum speed. The higher the efficiency of the motor, the higher this value may be set. If the engine does not reach maximum speed, reduce this parameter						
	Load	«K»–o		0 - 255	50				
	control	load c	MF						
	Parame-	contro	ol.						
	ter «K»		0.055	4.000					
	Load	«l»–co		0 - 255	100				
	Parame-		(inertia) of the motor. The higher the momentum of the motor (large flywheel or bigger motor), the lower this value has to be set.						
	ter «l»								
	BEMF	0-100	%. Defines the "Strengh" of the BEMF at minimum speed st	ер	0 - 255	255			
	Influence at VMin								
	Sound	Maste	er volume for all sounds.		0 - 192	192			
	volume								
	«Master»								

V	Name	Description		ange Default		Name	Description				e Default
4	Brake	If the actual loco speed step is smaller than or equals the value indicated		100	124	Extended	Additional important settings for decoders			-	24
sound		here, the brake sound is triggered.				Configura-	Bit Description Val		alue		
	threshold					tion #2	0	Bi-directional bit: Enable driving direction when shifting	1		
	«Brake							direction.			
	On»		0 - 255					Disable driving direction.	0		
5 Brake		If the actual loco speed step is smaller than the one indicated here (up		25			1	Disable decoder lock with CV 15 / 16	0		
	sound	to 255), the brake sound will be switched off again						Enable decoder lock with CV 15 / 16	2		
	threshold						2	Disable prime mover startup delay	0		
	«Brake							Enable prime mover startup delay	4		
_	Off»						3	Disable serial protocol for C-Sinus	0		
6	Forward	Divided by 128 is the factor used to multiply the motor voltage when	0 - 255	128				Enable serial protocol for C-Sinus	8		
-	Trim	driving forward. The value 0 deactivates the trim.	0 - 255				4	Adaptive regulation frequency	0		
/-	Speed table	Defines motor voltage for speed steps. The values "in between" will be	0 - 255	-			5	Constant regulation frequency	16		
4 r	Reverse	interpolated. Divided by 128 is the factor used to multiply the motor voltage when	0 - 255	128			5	Motor safety when blocking. Motor is not switched off when blocked.			
5	Trim	driving backwards. Value 0 deactivates the trim.	0 - 255	120					0 32		
12	Power Fail	The time that the decoder bridges via the PowerPack after an interrup-	0 - 255	50				avoid burnout	32		
15	Bypass	tion of voltage. Unit: A multiple of 0.016384 sec.	0-255	50	100	Starting		avoid burnout		0 - 255	30
16	Slow speed	Frequency of BEMF measurement in 0.1 milliseconds at speed step 1	50 - 200	50	125	voltage				0 - 255	50
BEMF			50 200	0 50		Analog DC					
	Sampling				126	Maximum				0 - 255	130
	period				120	speed				0-255	150
	penou					Analog DC					
17	Full speed	Frequency of BEMF measurement in 0.1 milliseconds at speed step 255		150	127	Starting	(For	LokSound 5 Multiprotocol decoders only)		0 - 255	50
	BEMF					voltage AC	(· •·	(			
					128	Maximum	(For LokSound 5 Multiprotocol decoders only)			0 - 255	150
	period					speed					
						Analog AC					
18 Slow speed Length of th		ength of the BEMF measuring gap in 0.1 milliseconds at speed step 1 1	10 - 20	150	134	ABC-Mode	Threshold, from which asymmentry on ABC shall be recognised.			4 - 32	12
	BEMF Mea-					"Sensibil-					
	surement					ity"					
	gap length	ngth			155	Notch	Notch Point 1 - Notch Point 8: The internal speed step where the diese		el	0 - 255	
	VMin				-	Points	engi	ine sound notches to the next Notch (Not for all sound projects)			
			10 - 20		162						
19	Full speed	The second		15	163			n Select CV		0 - 255	0
	BEMF Mea-	255			164	Sound	Bell	Select CV		0 - 255	0
	surement					CV10					
	gap length				165	Sound	Brake Squeal Select CV			0 - 255	0
	Vmax				100	CV11 Sound	A 14 F	Druge Calast CV		0 - 255	0
					166		Air L	Dryer Select CV		0 - 255	0
						CV12					

#### Warnings

- Do not expose to wet and humid conditions. Avoid mechanical force or pressure on the decoder
- Only use the minimum amout of solder needed.
- Always disconnect power before handling the decoder.
- Never wrap the decoder in electrical tape, as this may cause overheating.
- Make sure that neither the decoder nor any blank wire ends may come into contact with
- the engine chassis (risk of short circuit).
- Make sure that no wires are squeezed/cut when reassembling the locomotive

• Never operate a LokSound decoder unattended.

## Requirements for Installation

The locomotive must be in perfect operating condition prior to the conversion: Only a locomotive with faultless mechanical properties and smooth running characteristics in analogue mode is worth converting to digital. Check and replace all wear and tear parts such as motor brushes, wheel contacts, light bulbs etc., if necessary.

## Installing the Decoder

## Locomotives with 8-pin interface

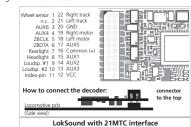
Some LokSound decoders are supplied with an 8-pin plug (refer to Fig 1). Remove the dummy plug from the socket. Insert the plug of the decoder in such a way that pin 1 of the plug (this is the side with the red / orange wires) sits next to the corner of the socket that is usually predicted by the second secon marked with \*, +, • or "1".

Do not rely on the assumption that the wires of the harness have to face in a certain direction the only reliable reference is the marking of pin 1.



## Locomotives with 21MTC interface

Some LokSound decoders are equipped with a 21MTC interface (fig. 2) You can insert the decoder in two ways: either the pins are put through the decoder (most common); the socket of the decoder remains visible after installation (mounting on top) or the decoder is inserted in such a way that the pins go straight into the socket. Which of the two mounting positions is the correct one depends solely on the locomotive. The position of the marker-pin is the crucial indicator. Plug the decoder into the socket in such a way that the locomotive interface corresponds with the decoder. Do not apply too much pressure when inserting the plug. The decoder must go in without force.



Locomotives without interface

All LokSound decoders have an interface (plug). There is no "wires-only" version. Please remove the plug at the end of the harness should hard wiring become necessary. First, please cut all wires installed in the locomotive. Take special care to remove any connec-tions to the chassis (ground): the motor leads must be positively potential-free, in other words they may not have any contact to the chassis or body or the wheels and wheel contacts. Figure 3 and Figure 4 shows all connections.

#### Function outputs

- You can wire all kind of loads to the function outputs.
- Please make sure that the load does not exceed the permitted maximum current and there are no short circuits. The outputs of the LokSound have protection but if an external voltage is applied, the outputs may suffer damage or destruction.
- Only install bulbs rated 16V or higher and with a nominal current draw, that does not exceed 50 mA. If you like to use LEDs, a resistor with a rating between 470 Ohms and 2.2 kOhms need to be wired in series. Running the LED without resistor will lead to their immediate

# DCC Operation

#### Enter the value 08 into CV 08.

To complete the reset, power to the decoder must be interrupted.

Volume Control

**BEMF** Autotune Function quickly take off then stop.

# **Quick Start Guide**

Edition 6, May 2023



1.50A continuous load / 2.00 A peak load 0.75A continuous load / 1.00 A peak load 8 pin and 21MTC decoders Next18 / Select Micro and V4.0 decoders 8 pin decoders 10 outputs (10 powered) ction outputs Up to 14 outputs (10 powered 4 logic) 21MTC decoders Next18 / LokSound 5 Micro decoders Audio amplifier: 2W @ 4 Ohm load Speaker impedance 4 - 16 Ohms Memory capacity 128 MBit Up to 9 outputs (6 powered, 3 logic) 10 sound channels, each up to 16 Bit 31.250 kHz HiFi Quality Over 280 different sounds!

## LokSound 5 DCC Direct

The LokSound 5 DCC Direct is unique as it was designed to fit in multiple brands of loco-motives. Please use the same mounting method as the Manufacturer's light board. This will insure a seemless installation.

On the LokSound 5 DCC Direct Board we have already added a resistor with 2.2k for each function output. This will result in a current between 8mA and 10mA suitable for most loco-motives. Thus you can directly connect your LEDs without thinking of resistor values. However, should you use bulbs consider the following:

First locate the appropriate soldering bridge on the LokSound 5 DCC Direct Board (see dia-gram above) for the output desired. Use a small amount of solder to connect the two soldering pads. This will bypass the installed 2.2k resistor.

If the bulbs to be used are less than 16V types, please add a resistor between the LokSound 5 DCC Direct and the bulbs.

- Athearn: 2 1.5 Volt Bulbs 360-510Ohms (Front or rear lights)
- Athearn: 1 1.5 Volt Bulb 680-1K Ohm (Acc. Lights)
- •Atlas: Resistors may already be attached to Factory LED's, you may be also bypass the Lok-Sound 5 DCC Direct installed 2.2k resistors

#### PowerPack

You can solder a powerful energy buffer to all LokSound 5 or LokSound 5 micro decoders. The connection diagram figure 3 and figure 4 shows you how to do it. This "PowerPack" allows your locomotive to keep running for 2 seconds without power.

- ESU supplies under the article number 54671 or 54672 suitable PowerPack modules. Please do ONLY use these.
- The PowerPack only operates in digital mode. It automatically turns off on analogue layouts. • It may take up to two minutes to fully charge the capacitor ("GoldCap"). Therefore, the
- time bridged with the energy buffer depends on the current draw of your locomotive and the charge-up time. • Further information about how to use the PowerPack module is to be found in the "Power-
- Pack module" manual. • The LokSound 5 L, LokSound 5 L DCC and LokSound 5 XL have an integral PowerPack
- matching the higher current needed by models of the larger gauges. Additional buffering with capacitors or further PowerPacks is neither intended nor necessary.

**1** The time to be bridged with the PowerPack can be set in CV 113. Output AUX9 or AUX7 needs to be set to "PowerPackControl".

#### Configure the PowerPack

When you connect an external capacitor or PowerPack, you are able to make the decoder switch off after a certain time. CV113 is responsible for that, since you are able to determine at what time the decoder is to switch off (as a multiple of 0.0328 seconds). You should set a time between 0.3 and 1.0 seconds to prevent your locos from driving too far during an emergency.

A For the PowerPack to work, the function output responsible for the charge (typically AUX9 for LokSound, AUX7 for LokSound micro) must be configured to the "PowerPackControl" function.

Set CV 31 = 16, CV 32 = 0 first.

Then set CV339 = 31 for LokSound (AUX9)

Then set CV323 = 31 for LokSound micro (AUX7).

1 The LokSound works with any DCC system. Remove any capacitors that are wired into the track feeders. This could impair the functionality of the decoder.

#### The address is set to 03 with 28 speed steps.

You can reset the decoder to the default settings at any time. In most cases POM program-ming will not work to reset a decoder. Please use a separate programming track.

Master volume is controlled with CV 63. The range is 0 - 192.

Individual volumes (CVs as shown) range from 0 - 128.

Set CV54 to a value of 0, place loco on Mainline and press F1 on your throttle. Loco will

Please leave about 5 feet in front of the loco for movement. Once loco stops BEMF is Auto tuned and you continue to operate as normal

You may adjust the BEMF values found by the Auto Tune function manually after autotune.



